

Core IO - CR-IO-40MULTI User Manual

40 Point Mudbus I/O Module I6 DI, 8 DO, 8 UI, 8 UO/DI



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Overview



In many installations, having cost-effective, robust, and simple hardware becomes a key factor in winning a project. The Core range provides the perfect solution to meet these criteria. Innon have collaborated with Atimus, a company with a wealth of experience in the field, and are proud to present Core IO!

The 40 MULTI is a 40 point I/O device providing a perfect balance of analogue and digital inputs and outputs. The device supports a variety of sensor types, allows the use of pulse counters and integrates a watchdog to safely position its outputs in case of a network failure.

BEMS communication is based on the robust and well-proven Modbus RTU over RS485 or Modbus TCP (IP model only).

The configuration of the device can be achieved through the network using either the web interface (IP version only) or Modbus configuration registers or by using an Android device and connecting over Bluetooth using the dedicated app.

This Core IO model

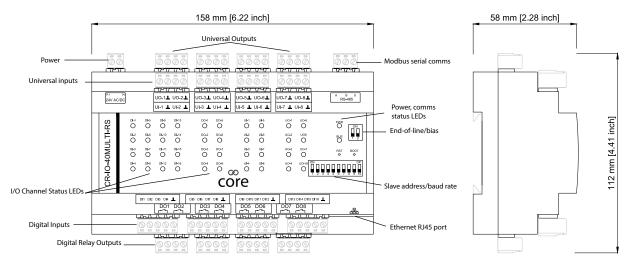
The CR-IO-40MULTI-RS and the CR-IO-40MULTI-IP modules come with 8 universal inputs, 8 universal outputs, 16 digital inputs and 8 relay outputs.

The CR-IO-40MULTI-RS only comes with the RS485 port, while the CR-IO-40MULTI-IP comes with both RS485 and IP ports.

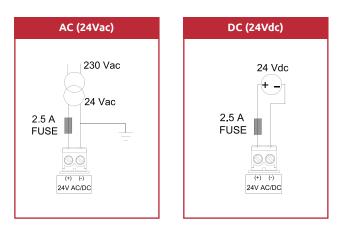
Both models come with Bluetooth on-board, so configuration can be achieved using an Android device and the dedicated app. The IP CR-IO-40MULTI-IP model also integrates a web server configuration interface, accessible via a PC web browser.

HARDWARE

Overview

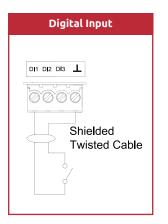


Wiring Power Supply

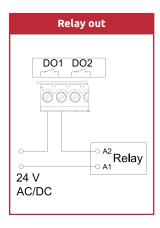


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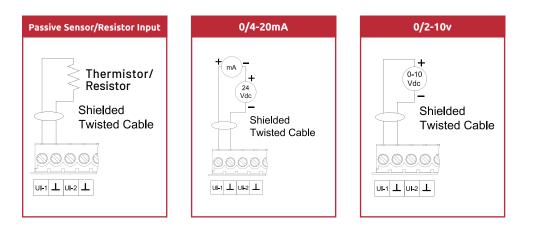
Wiring Digital Inputs (DI)



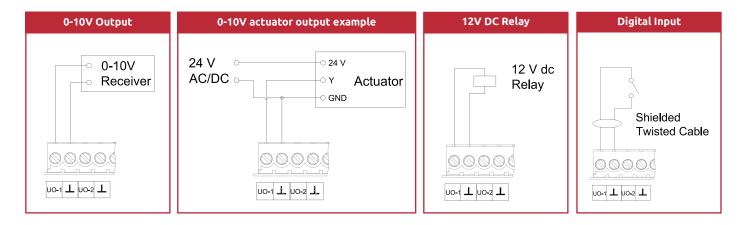
Wiring Digital Outputs (DO)



Wiring Universal Inputs (UI)



Wiring Universal Outputs (UO) - Including Use as Digital Input



Wiring the RS485 network

Some useful links to our knowledge base website:

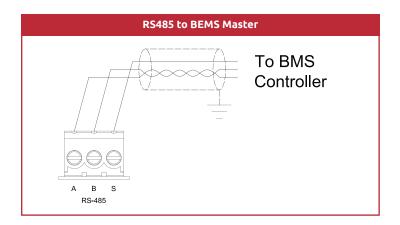
How to wire an RS485 network

https://know.innon.com/howtowire-non-optoisolated

How to terminate and bias an RS485 network

https://know.innon.com/bias-termination-rs485-network

Please note - both IP and RS versions can use the RS485 port to respond to serial Modbus master comms from the BEMS, but neither version can use the RS485 port to act as a Modbus master or gateway.



Front LED Panel

The LEDs in the front panel can be used to get direct feedback on the status of the I/Os of Core IO and more general information.

Below are some tables that will help decode each LED behaviour –

| DI 1 to 16 | | | | | | | |
|--------------------|-------------------|-------------------------------|--|--|--|--|--|
| Digital Input Mode | Conditions | LED Status | | | | | |
| Direct | Open circuit | LED OFF | | | | | |
| Direct | Short circuit | LED ON | | | | | |
| Reverse | Open circuit | LED ON | | | | | |
| | Short circuit | LED OFF | | | | | |
| Pulse input | Receiving a pulse | LED blinks ON for every pulse | | | | | |

| DO 1 to 8 | | | | | | |
|---------------------|-------------------|------------|--|--|--|--|
| Digital Output Mode | Conditions | LED Status | | | | |
| Direct | Output active | LED ON | | | | |
| Direct | Output not active | LED OFF | | | | |
| Reverse | Output active | LED OFF | | | | |
| | Output not active | LED ON | | | | |

| UI 1 to 8 | | |
|--------------------|----------------|----------------------------------|
| Digital Input Mode | Conditions | LED Status |
| 0-10V | | |
| 2-10V | | Blinks ON x3 times in 50ms |
| 0-20mA | Always | intervals, then pauses for 800ms |
| 4-20mA | | |
| PT1000 | | |
| NI1000 DIN | | |
| NI1000 LG | | |
| NTC1K8 | Open Circuit | LED ON then OFF blinking |
| NTC2K2 | | |
| NTC3K3 | Short Circuit | LED ON |
| NTC10K3A1 | | |
| NTC10K4A1 | Sensor reading | LED OFF |
| NTC10K CAREL | | |
| NTC20K6A1 | | |
| RESISTOR VALUE | | |
| | | |

| UO 1 to 8 | | | | | | | |
|------------------------------|-------------------|-------------------------------|--|--|--|--|--|
| Input/Output Mode | Conditions | LED Status | | | | | |
| | Min value out | LED OFF | | | | | |
| 0-10V Output 2-10V Output | Value in between | LED blinking 2s ON, 2s OFF | | | | | |
| | Max value out | LED ON | | | | | |
| Digital Input Direct | Open circuit | LED OFF | | | | | |
| | Short circuit | LED ON | | | | | |
| | Open circuit | LED ON | | | | | |
| Digital Input Reverse | Short circuit | LED OFF | | | | | |
| Pulse input | Receiving a pulse | LED blinks ON for every pulse | | | | | |
| Digital Output Direct | Output active | LED ON | | | | | |
| | Output not active | LED OFF | | | | | |
| Digital Output Deverse | Output active | LED OFF | | | | | |
| Digital Output Reverse | Output not active | LED ON | | | | | |

| BUS and PWR | | | | | | | |
|-------------|---------------------------|-----------------------------|--|--|--|--|--|
| LED | Conditions | LED Status | | | | | |
| PWR | Core IO not powered | LED OFF | | | | | |
| | Core IO correctly powered | LED ON | | | | | |
| | Data being received | LED blinks <mark>RED</mark> | | | | | |
| BUS | Data being transmitted | LED blinks BLUE | | | | | |
| | Bus polarity problem | LED ON RED | | | | | |

CONFIGURE I/O

Digital Inputs

Digital Inputs can have a clean/volt free contact connected to Core IO to read its open/closed status.

Each digital input can be configured to be either:

- Digital Input direct
- Digital Input reverse
- Pulse input

While the "direct" and "reverse" mode would basically return status "False (0)" or "True (1)" when the contact is either open or closed, the third mode "pulse input" is used to return a counter value increasing by 1 unit every time the digital input closes.

A dedicated chapter on the pulse input topic is available later in this manual.

The pulse input can count effectively up to a frequency of 100Hz, with 50% duty cycle.

Digital Outputs (Relay)

The Digital Outputs are driven by relays.

Each Digital Output can be configured to be either:

- Digital Output direct
- Digital Output reverse (effectively reversing the logic of the output status)

For every Digital Output it is possible to configure the desired status when the "Watchdog" function is triggered (BEMS offline for over a timeout delay).

Universal Inputs

Universal Inputs are used to connect analogue signal inputs to Core IO.

A variety of sensors and signals can be connected to a Universal Input. In terms of active signals, both voltage (0-10V, 2-10V) and current (0-20mA, 4-20mA) are supported directly. As for passive sensors, a long list of different thermistor types is available, on top of the direct resistance reading (in case you prefer to run the conversion to temperature in the BEMS strategy for dedicated types of sensors)

Here is a list of the supported input types for each individual Universal Input:

- Analogue Input 0-10V
- Analogue Input 2-10V
- Analogue Input 0-20 mA
- Analogue Input 4-20 mA
- PT1000
- NI1000 DIN
- NI1000 LG
- NTC1K8
- NTC2K2
- NTC3K3
- NTC10K3A1
- NTC10K4A1
- NTC10KCAREL
- NTC20K6A1
- Resistor Value

Universal Outputs (Digital Inputs)

Universal Outputs are primarily used as analogue outputs (0-10V, 2-10V). They can also be configured in "digital output" mode, which is just sending "0V" at a low state, "10V" at high state with 20mA max current.

Despite the name "outputs", the Universal Outputs can be configured as digital inputs as well to extend the number of digital inputs available. They can also be configured as inputs for pulse counting like standard digital inputs can with the same 100Hz/50% duty cycle property.

As per Digital Outputs, Universal Outputs can also be configured with a default output position in case the Watchdog function triggers (BEMS offline for over a timeout delay).

Here is a list of the available options that can be selected to be used for Universal Outputs:

- Analogue Output 0-10V
- Analogue Output 2-10V
- Digital Output direct
- Digital Output reverse
- Digital Input direct
- Digital Input reverse
- Pulse input

Pulse Counting

Digital Inputs and Universal Outputs can be configured specifically to work as pulse counting inputs.

The counting maximum readable frequency is 100Hz, with a duty cycle of 50% and the maximum "contact closed" readable resistance is 50ohm.

When an input is configured to count pulses, a number of Modbus Registers are available with information and commands specifically for the pulse counting function.

The pulse input will, in fact count 2 totalizers as follows –

• The first one is continuous; it will increase by one unit for every pulse received and will keep counting until a reset command is sent over Modbus

• The other totalizer is timed. Basically, it will also increase by one unit for every pulse received but will count only for a specified (adjustable) time (in minutes). When the time expires, this second counter will start counting again from "0" immediately, repeating the cycle, but will hold the last resulting value for a minute in the register (counting the next cycle in the background)

Each pulse counting input has the following Modbus registers associated with it –

• **counter (totalizer):** this is the main totalizer. It will go back to "0" only if a reset command is sent, or if Core IO is power cycled – you can also write to this value to restore a previous count if replacing a module or to reset to 0

• **counter (timer):** this is the second totalizer, the timed one. It will go back to "0" every time the timer reaches the maximum set value (with a delay of 1 minute), or if Core IO is power cycled. If the counter reset is activated, the counts within the timed cycle will be ignored and the counter timer reset to 0. The reset will not reset this count to 0 after it has finished a timed cycle and is displaying the result for 1 minute

• **counter timer:** this data point returns the current time of the counter in minutes. It will of course, go back to "0" when it reaches the maximum set value

• **counter timer set:** using this data point you can configure the duration of the timer for the second totalizer (max set value) in minutes. This value is stored within the Core IO memory

• **counter reset:** using this data point, you can reset the totalizer counter to value "0" and the timed counter will discard counts up to that point in the timed cycle and reset its timer to 0. Core IO will self-reset this data point to value "0" once the command has been executed

CONFIGURING THE DEVICE

Fixed Settings

The RS485 Modbus Slave communication have some settings that are fixed as follows –

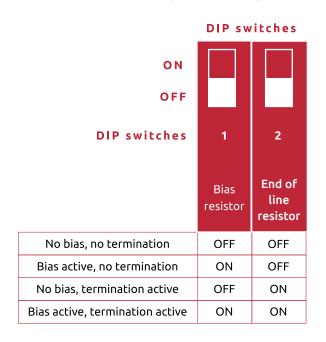
- 8-bit data length
- 1 stop bit
- Parity NONE

DIP Switch Setting

The DIP switches are used to configure the other RS485 settings and the Modbus slave address thus–

- RS485 End-Of-Line (EOL) resistor
- RS485 Bias resistors
- Modbus Slave Address
- RS485 Baud-Rate

The bank of two EOL (End-Of-Line) blue DIP switches are configured as follows –



Please check our dedicated knowledge base article available at the website <u>http://know.innon.com</u> where we explain in detail the use of the termination and bias resistors on RS485 networks.

The Modbus ID and baud rate DIP switches are configured as follows –

| ON | | | | | | | | | | |
|---------------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------------------|
| | | | | | | | | | | |
| DIP switches | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 (reserved) |
| Slave address | | | | | | | | | | Baud rate |
| 1 | ON | OFF | 4800 Kbps |
| 2 | OFF | ON | OFF | OFF | OFF | OFF | ON | OFF | OFF | 9600 Kbps |
| 3 | ON | ON | OFF | OFF | OFF | OFF | OFF | ON | OFF | 19200 Kbps |
| 4 | OFF | OFF | ON | OFF | OFF | OFF | ON | ON | OFF | 38400 Kbps |
| 5 | ON | OFF | ON | OFF | OFF | OFF | OFF | OFF | ON | 57600 Kbps |
| 6 | OFF | ON | ON | OFF | OFF | OFF | ON | OFF | ON | 76800 Kbps |
| 7 | ON | ON | ON | OFF | OFF | OFF | OFF | ON | ON | 115200 Kbps |
| 8 | OFF | OFF | OFF | ON | OFF | OFF | ON | ON | ON | 230400 Kbps |
| 9 | ON | OFF | OFF | ON | OFF | OFF | | | | |
| 10 | OFF | ON | OFF | ON | OFF | OFF | | | | |
| 11 | ON | ON | OFF | ON | OFF | OFF | | | | |
| 12 | OFF | OFF | ON | ON | OFF | OFF | | | | |
| 13 | ON | OFF | ON | ON | OFF | OFF | | | | |
| 14 | OFF | ON | ON | ON | OFF | OFF | | | | |
| 15 | ON | ON | ON | ON | OFF | OFF | | | | |
| 16 | OFF | OFF | OFF | OFF | ON | OFF | | | | |
| 17 | ON | OFF | OFF | OFF | ON | OFF | | | | |
| 18 | OFF | ON | OFF | OFF | ON | OFF | | | | |
| 19 | ON | ON | OFF | OFF | ON | OFF | | | | |
| 20 | OFF | OFF | ON | OFF | ON | OFF | | | | |
| 21 | ON | OFF | ON | OFF | ON | OFF | | | | |
| 22 | OFF | ON | ON | OFF | ON | OFF | | | | |
| 23 | ON | ON | ON | OFF | ON | OFF | | | | |
| 24 | OFF | OFF | OFF | ON | ON | OFF | | | | |
| 25 | ON | OFF | OFF | ON | ON | OFF | | | | |
| 26 | OFF | ON | OFF | ON | ON | OFF | | | | |
| 27 | ON | ON | OFF | ON | ON | OFF | | | | |
| 28 | OFF | OFF | ON | ON | ON | OFF | | | | |

Slave address DIP switch settings, continued.

| ON Off | | | | | | |
|---------------|-----|-----|-----|-----|-----|-----|
| DIP switches | 1 | 2 | 3 | 4 | 5 | 6 |
| Slave address | | | | | | |
| 29 | ON | OFF | ON | ON | ON | OFF |
| 30 | OFF | ON | ON | ON | ON | OFF |
| 31 | ON | ON | ON | ON | ON | OFF |
| 32 | OFF | OFF | OFF | OFF | OFF | ON |
| 33 | ON | OFF | OFF | OFF | OFF | ON |
| 34 | OFF | ON | OFF | OFF | OFF | ON |
| 35 | ON | ON | OFF | OFF | OFF | ON |
| 36 | OFF | OFF | ON | OFF | OFF | ON |
| 37 | ON | OFF | ON | OFF | OFF | ON |
| 38 | OFF | ON | ON | OFF | OFF | ON |
| 39 | ON | ON | ON | OFF | OFF | ON |
| 40 | OFF | OFF | OFF | ON | OFF | ON |
| 41 | ON | OFF | OFF | ON | OFF | ON |
| 42 | OFF | ON | OFF | ON | OFF | ON |
| 43 | ON | ON | OFF | ON | OFF | ON |
| 44 | OFF | OFF | ON | ON | OFF | ON |
| 45 | ON | OFF | ON | ON | OFF | ON |
| 46 | OFF | ON | ON | ON | OFF | ON |
| 47 | ON | ON | ON | ON | OFF | ON |
| 48 | OFF | OFF | OFF | OFF | ON | ON |
| 49 | ON | OFF | OFF | OFF | ON | ON |
| 50 | OFF | ON | OFF | OFF | ON | ON |
| 51 | ON | ON | OFF | OFF | ON | ON |
| 52 | OFF | OFF | ON | OFF | ON | ON |
| 53 | ON | OFF | ON | OFF | ON | ON |
| 54 | OFF | ON | ON | OFF | ON | ON |
| 55 | ON | ON | ON | OFF | ON | ON |
| 56 | OFF | OFF | OFF | ON | ON | ON |
| 57 | ON | OFF | OFF | ON | ON | ON |
| 58 | OFF | ON | OFF | ON | ON | ON |
| 59 | ON | ON | OFF | ON | ON | ON |
| 60 | OFF | OFF | OFF | ON | ON | ON |
| 61 | ON | OFF | ON | ON | ON | ON |
| 62 | OFF | ON | ON | ON | ON | ON |
| 63 | ON | ON | ON | ON | ON | ON |

Bluetooth and Android App

Core IO has built-in Bluetooth which allows the Core Settings app running on an Android device to configure the IP settings and I/O.

Please download the app from Google Play – search for "core settings" Download and install the app, then check/make the following settings changes –

- Open your phone settings (drag down from top, press "cog" icon)
- Click on "Apps"
- Select "Core Settings" app
- Press "Permissions"
- Press "Camera" set to "Allow only while using the app"
- Go back then press "Nearby devices" set to "Allow"

When you run the app, the camera will switch on, and you will need to use it to read the QR code on the module you wish to set up, i.e. –

| 15:05 🕲 | ₩ 🕈 🕈 46 🖌 🔒 90% |
|---------------|------------------|
| CORE Settings | |
| | |

The Android device will ask you to allow the Bluetooth devices to pair on the first connection, watch out for the notifications on your device and accept them.

| vodafone | e TR WATE , III 🛜 🖨 🌲 🖸 | | | | ⓒ ≵%95 깯 10:25 | |
|----------|-------------------------|-----|------|--------|----------------|-----------------|
| I/O | I/O Mode | Min | Max | Offset | Value | |
| UI1 | PT1000 | 0 | 1000 | 0 | 226 | |
| UI2 | NTC10K3A1 | 0 | 1000 | 0 | 227 | |
| UI3 | 0-10 V | 0 | 1000 | 0 | 0 | |
| UI4 | 0-10 V | 0 | 1000 | 0 | 0 | |
| UI5 | 0-10 V | 0 | 1000 | 0 | 0 | 0 |
| UI6 | 0-10 V | 0 | 1000 | 0 | 0 | |
| UI7 | 0-10 V | 0 | 1000 | 0 | 0 | \triangleleft |
| UI8 | 0-10 V | 0 | 1000 | 0 | 0 | |
| U01 | AO 0-10 VOLTAGE | 0 | 1000 | 0 | 0 | > |
| | ETHERNET | | | UPDATE | | |

Once connected, you will land on the I/O setup screen, where you can set up the I/O and read input and output current values –

| vodafone T | r 🏧 📶 🗟 🕅 | ê O | | | | ତ \$%96 💷 10:19 | |
|------------|------------|----------|-----|-----|--------|-----------------|--------------------|
| 1/0 | | I/O Mode | Min | Max | Offset | Value | |
| UI1 | 0-10 V | 0-10 V | | | ۲ | 0 | |
| 012 | 0-10 V | | | | | 0 | |
| UI3 | 0-10 V | 2-10 V | | | 0 | 0 | |
| UH | 0-10 V | | | | | 0 | \sim |
| UI5 | 0-10 V | 0-20 mA | | | 0 | 0 | 0 |
| UI6 | 0-10 V | | | | | 0 | |
| U17 | 0-10 V | 4-20 mA | | | 0 | 0 | \bigtriangledown |
| UIB | 0-10 V | | | | _ | 0 | |
| U01 | AO 0-10 VO | PT1000 | | | 0 | 0 | > |
| | | | | | | | |

Use the drop-down arrows in the "I/O Mode" column to select the type of input or output type by clicking on the respective radio button –

Input data into the white boxes under Min, Max, and Offset as required. Please note – the Min and Max parameters do not apply to all input/output types. E.g. thermistor inputs are not affected by Min or Max settings, whereas 0/2-10v and 0/4-20mA use them to scale the input voltage/current being measured to provide a meaningful reading in the Modbus register.

Once you make a change or number of changes, the "UPDATE" button on the bottom right will go from greyed-out to white; press this to commit your changes.

Click on the "ETHERNET" button (bottom left) to setup the required IP settings. Set and commit data as per the I/O method above.

Click on "MODE" button (bottom left) to get back to the I/O settings.

| IpAdress IP | IpAdres | s GATEWAY | / IpAdress SUBNET | IpAdress Mae | c | | | |
|---------------|-----------|-----------|-------------------|-----------------|-----|--|---|--------------------|
| 192.168.1.175 | 192.168.1 | .1 | 255.255.255.0 | 98:F4:AB:26:DC: | :AB | | | |
| ip Adress:192 | 168 | 1 | 175 | | | | C | |
| MASK: 255 | 255 | 255 | 0 | | | | | |
| Gateway: 192 | 168 | 1 | 1 | | | | | |
| | | | | | | | | |
| | | | | | | | | |
| | | | | | | | < | \bigtriangledown |
| | | | | | | | | |
| | | | | | | | | > |
| | | MODI | E | | 1 | | | |

Ethernet Port and Web Server Configuration (IP version only)

For the IP models of Core IO, a standard RJ45 socket is available to be used for:

- Modbus TCP (slave) communication
- Web server access to configure the device

The IP models still provide access on the RS485 port for Modbus RTU (slave) communication on these models, so the user can decide which one to use to connect the BEMS to Core IO.

The default settings of the IP port are:

| IP address: | 192.168.1.175 |
|-------------------------|----------------|
| Subnet: | 255.255.255.0 |
| Gateway address: | 192.168.1.1 |
| Modbus TCP port: | 502 (fixed) |
| Http port (web server): | 80 (fixed) |
| Web server user: | atimus (fixed) |
| Web server password: | HD1881 (fixed) |

IP address, subnet and gateway address can be changed from the Bluetooth Android app or from the webserver interface.

The web server interface looks and works in much the same way as the Core Settings app described in the previous section.

Watchdog

Watchdog is an internal function of Core IO used to check if a master is online to control the I/O, and if it is not, it can position the outputs to a pre-configured (default) pattern. This could be useful to keep a critical plant running in the event of a Modbus comms or main BEMS controller failure.

A "BEMS timeout" point is available to set the watchdog delay (decimal register address 999). If the BEMS does not send any command to Core IO within the "BEMS timeout" set time, Core IO will determine the BEMS as being offline and will position all the available outputs to their "default" positions. The "default" configuration is available as an individual Modbus configurable point for each output.

The "BEMS timeout" is expressed in "seconds /100". This means that the writing value "3000" will correspond to a timeout of "30 seconds".

The watchdog function can be disabled by setting "BEMS timeout" to 0.

Note for Niagara users: make sure at least one of the network points is constantly subscribing (used within the strategy, history or alarm extension associated or visualized on a page) so that Niagara sends a command to Core IO and the watchdog feature doesn't kick in when not needed.

BEMS POINT LISTS

Modbus Register Types

Unless otherwise stated in the tables, all I/O point values/statuses and settings are held as Holding Register Modbus data type and use a single register (16 bit) to represent either an Integer (Int, range 0 - 65535) or Signed Integer (Sint, range -32768 – 32767) type of data. Please refer to the "Range" column to determine which is used (if column shows negative Min setting or refers to another setting that is negative, use Signed Integer)

Pulse count registers are 32-bit long, unsigned registers, i.e. two consecutive 16-bit registers combined, and their byte order is sent in little endian, i.e. –

- Niagara/Sedona Modbus driver 1032
- Teltonika RTU xxx 3412 also use 2 x "Register count/values" to obtain all 32 bits

For some Modbus master devices, the decimal and hex register addresses in the table will need to be incremented by 1 to read the correct register (e.g. Teltonika RTU xxx)

Bit-field data type uses individual bits from the 16 bits available on the Modbus register to provide multiple Boolean information or command by reading or writing a single register.

Please note – digital output points can be controlled by integer registers AND bit-field registers concurrently and are not linked to each other directly by reading or writing in any way – these will act on the output in an OR logical way, i.e. if either register is set to 1 or True, the output will see this as a positive command signal. Therefore, if changing from one control type to another and the new register requires exclusive control, the old register must first be set to 0 or False.

Input and Output Scaling

The holding registers associated with inputs and outputs can be scaled as follows –

- Thermistors and Resistor types precision is fixed to 1 decimal place, divide by 10 to get actual temperature reading, i.e.
 - Modbus register value = 234, therefore temperature = 234/10 = 23.4°C
- Input 0/2-10V and 0/4-20mA types user defined, set Min and Max to precision required e.g.
 - 0-20mA detector with range of 0 to 100°C
 - Set Min to 0, Max to 1000, divide register value by 10 to get 1 decimal point precision actual temperature reading
 - Set Min to 0, Max to 10000 divide register value by 100 to get 2 decimal point precision actual temperature reading
- Output 0/2-10V user defined, set Min and Max to precision required e.g.
 - 0 to 10V output to valve
 - Set Min to 0, Max to 100 precision is 0.1V, e.g. register value set to 55 = output of 5.5V
 - Set Min to 0, Max to 1000 precision is 0.01V, e.g. register value set to 345 = output of 3.45V

Modbus Register Tables

| General F | General Points | | | | | | | | |
|-----------|----------------|----------------------------------|---|--------|------|--------|--|--|--|
| Decimal | Hex | Name | Details | Stored | Туре | Range | | | |
| 999 | 3E7 | BEMS timeout | Delay for the watchdog to engage when the module is offline, setting all outputs to "default" position. Value expressed in seconds /100, default value 3000 = 30 seconds (0 = disable watchdog function) | YES | R/W | 030000 | | | |
| 3002 | BBA | Firmware version - units | Most significant number for firmware version e.g. 2.xx | YES | R | 0-9 | | | |
| 999 | BBB | Firmware version - tenths | 2nd Most significant number for firmware version e.g. x.0x | YES | R | 0-9 | | | |
| 3002 | BBC | Firmware version - hundredths | 3rd Most significant number for firmware version e.g. x.x4 | YES | R | 0-9 | | | |

| Digital O | utput P | oints | | | | |
|-----------|---------|--------------|--|--------|------|-------|
| Decimal | Hex | Name | Details | Stored | Туре | Range |
| 51 | 33 | DO 1 mode | | | | |
| 52 | 34 | DO 2 mode | | | | |
| 53 | 35 | DO 3 mode | Disital Output made select | | | |
| 54 | 36 | DO 4 mode | Digital Output mode select: 0 = Digital Output direct | YES | R/W | 01 |
| 55 | 37 | DO 5 mode | 1 = Digital Output reverse | | | |
| 56 | 38 | DO 6 mode | | | | |
| 57 | 39 | DO 7 mode | | | | |
| 58 | 3A | DO 8 mode | | | | |
| 1 | 1 | DO 1 | | | | |
| 2 | 2 | DO 2 | | | | |
| 3 | 3 | DO 3 | | | | |
| 4 | 4 | DO 4 | Control Digital Output status: 0 = disengaged | NO | R/W | 01 |
| 5 | 5 | DO 5 | 1 = engaged | | | |
| 6 | 6 | DO 6 | | | | |
| 7 | 7 | DO 7 | | | | |
| 8 | 8 | DO 8 | | | | |
| 11 | В | DO 1-8 | Control Digital Output status by bit (bit 0 = DO 1) | NO | R/W | 01 |
| 91 | 5B | DO 1 default | | | | |
| 92 | 5C | DO 2 default | | | | |
| 93 | 5D | DO 3 default | Watchdog fall back value in case of connection lost. | | | |
| 94 | 5E | DO 4 default | Digital Output status: | YES | R/W | 01 |
| 95 | 5F | DO 5 default | 0 = disengaged | | | |
| 96 | 60 | DO 6 default | 1 = engaged | | | |
| 97 | 61 | DO 7 default | | | | |
| 98 | 62 | DO 8 default | | | | |

| Universa | Universal Output Points | | | | | | | |
|----------|-------------------------|--------------|--|--------|------|------------------------------|--|--|
| Decimal | Hex | Name | Details | Stored | Туре | Range | | |
| 501 | 1F5 | UO 1 mode | | | | | | |
| 502 | 1F6 | UO 2 mode | | | | | | |
| 503 | 1F7 | UO 3 mode | Universal Output mode select: 0 = Analog Output 0-10V | | | | | |
| 504 | 1F8 | UO 4 mode | 1 = Analog Output 2-10V 2 = Digital Input direct | YES | R/W | 06 | | |
| 505 | 1F9 | UO 5 mode | 3 = Digital Input reverse | | | | | |
| 506 | 1FA | UO 6 mode | 4 = Pulse input 5 = Digital Output direct | | | | | |
| 507 | 1FB | UO 7 mode | 6 = Digital Output reverse | | | | | |
| 508 | 1FC | UO 8 mode | | | | | | |
| 101 | 65 | UO 1 | | | | | | |
| 102 | 66 | UO 2 | Control Universal Output status (digital output mode): 0 = disengaged | | | | | |
| 103 | 67 | UO 3 | 1 = engaged | | | | | |
| 104 | 68 | UO 4 | Control Universal Output status (analogue output mode): | NO | R/W | Min register | | |
| 105 | 69 | UO 5 | value between "Min" register and "Max" register | | | Max register | | |
| 106 | 6A | UO 6 | Read Universal Output status (read only, digital input mode): | | | | | |
| 107 | 6B | UO 7 | 0 = inactive 1 = active | | | | | |
| 108 | 6C | UO 8 | | | | | | |
| 111 | 6F | UO 1-8 | Control Universal Output status by bit (only digital output mode, bit 0 = UO 1) | NO | R/W | 01 | | |
| 901 | 385 | UO 1 default | | | | | | |
| 902 | 386 | UO 2 default | Watchdog fall back value in case of connection lost. | | | | | |
| 903 | 387 | UO 3 default | | | | | | |
| 904 | 388 | UO 4 default | Universal Output status (digital output mode): 0 = disengaged | YES | R/W | Min register Max register | | |
| 905 | 389 | UO 5 default | 1 = engaged | | | Max register | | |
| 906 | 38A | UO 6 default | Universal Output status (analogue output mode): | | | | | |
| 907 | 38B | UO 7 default | value between "Min" register and "Max" register | | | | | |
| 908 | 38C | UO 8 default | | | | | | |
| 201 | С9 | UO 1 min | | | | | | |
| 202 | CA | UO 2 min | | | | | | |
| 203 | СВ | UO 3 min | | | | | | |
| 204 | СС | UO 4 min | Minimum value for Universal Outputs configured as Analog | YES | R/W | -10000 | | |
| 205 | CD | UO 5 min | Outputs | | | 10000 | | |
| 206 | CE | UO 6 min | | | | | | |
| 207 | CF | UO 7 min | | | | | | |
| 208 | D0 | UO 8 min | | | | | | |

| 301 | 12D | UO 1 max | | | | |
|-----|-----|--------------------------|--|-----|-----|-----------------|
| 302 | 12E | UO 2 max | | | | |
| 303 | 12F | UO 3 max | | | | |
| 304 | 130 | UO 4 max | Maximum value for Universal Outputs configured as Analog | YES | R/W | -10000 |
| 305 | 131 | UO 5 max | Outputs | | | 10000 |
| 306 | 132 | UO 6 max | | | | |
| 307 | 133 | UO 7 max | | | | |
| 308 | 134 | UO 8 max | | | | |
| 401 | 191 | UO 1 offset | | | | |
| 402 | 192 | UO 2 offset | | | | |
| 403 | 193 | UO 3 offset | | | | |
| 404 | 194 | UO 4 offset | Offset value for Universal Outputs configured as Analog | YES | R/W | -10000 |
| 405 | 195 | UO 5 offset | Outputs | | | 10000 |
| 406 | 196 | UO 6 offset | | | | |
| 407 | 197 | UO 7 offset | | | | |
| 408 | 198 | UO 8 offset | | | | |
| 121 | 79 | UO 1 counter (totalizer) | 32 bit long, total counter value (totalizer) (pulse input mode) | NO | R/W | 04294967 295 |
| 123 | 7B | UO 1 counter (timer) | 32 bit long, counter value for the running timer (pulse input mode) | NO | R | 04294967 295 |
| 125 | 7D | UO 1 counter timer | Running timer in minutes. Will reset once "counter timer set" reached and start again | NO | R | 014400 |
| 126 | 7E | UO 1 counter timer set | Timer duration configuration in minutes | YES | R/W | 014400 |
| 127 | 7F | UO 1 counter reset | Reset command to all counted values (goes back to "0" automatically) | NO | R/W | 01 |
| 221 | DD | UO 2 counter (totalizer) | 32 bit long, total counter value (totalizer) (pulse input mode) | NO | R/W | 04294967 295 |
| 223 | DF | UO 2 counter (timer) | 32 bit long, counter value for the running timer (pulse input mode) | NO | R | 04294967 295 |
| 225 | E1 | UO 2 counter timer | Running timer in minutes. Will reset once "counter timer set" reached and start again | NO | R | 014400 |
| 226 | E2 | UO 2 counter timer set | Timer duration configuration in minutes | YES | R/W | 014400 |
| 227 | E3 | UO 2 counter reset | Reset command to all counted values (goes back to "0" automatically) | NO | R/W | 01 |
| 321 | 141 | UO 3 counter (totalizer) | 32 bit long, total counter value (totalizer) (pulse input mode) | NO | R/W | 04294967 295 |
| 323 | 143 | UO 3 counter (timer) | 32 bit long, counter value for the running timer (pulse input mode) | NO | R | 04294967 295 |
| 325 | 145 | UO 3 counter timer | Running timer in minutes. Will reset once "counter timer set" reached and start again | NO | R | 014400 |
| 326 | 146 | UO 3 counter timer set | Timer duration configuration in minutes | YES | R/W | 014400 |
| 327 | 147 | UO 3 counter reset | Reset command to all counted values (goes back to "0" automatically) | NO | R/W | 01 |
| | | | | | | |

| 421 | 1A5 | UO 4 counter (totalizer) | 32 bit long, total counter value (totalizer) (pulse input mode) | NO | R/W | 04294967 295 |
|-----|-----|--------------------------|--|-----|-----|-----------------|
| 423 | 1A7 | UO 4 counter (timer) | 32 bit long, counter value for the running timer (pulse input mode) | NO | R | 04294967 295 |
| 425 | 1A9 | UO 4 counter timer | Running timer in minutes. Will reset once "counter timer set" reached and start again | NO | R | 014400 |
| 426 | 1AA | UO 4 counter timer set | Timer duration configuration in minutes | YES | R/W | 014400 |
| 427 | 1AB | UO 4 counter reset | Reset command to all counted values (goes back to "0" automatically) | NO | R/W | 01 |
| 521 | 209 | UO 5 counter (totalizer) | 32 bit long, total counter value (totalizer) (pulse input mode) | NO | R/W | 04294967 295 |
| 523 | 20B | UO 5 counter (timer) | 32 bit long, counter value for the running timer (pulse input mode) | NO | R | 04294967 295 |
| 525 | 20D | UO 5 counter timer | Running timer in minutes. Will reset once "counter timer set" reached and start again | NO | R | 014400 |
| 526 | 20E | UO 5 counter timer set | Timer duration configuration in minutes | YES | R/W | 014400 |
| 527 | 20F | UO 5 counter reset | Reset command to all counted values (goes back to "0" automatically) | NO | R/W | 01 |
| 621 | 26D | UO 6 counter (totalizer) | 32 bit long, total counter value (totalizer) (pulse input mode) | NO | R/W | 04294967 295 |
| 623 | 26F | UO 6 counter (timer) | 32 bit long, counter value for the running timer (pulse input mode) | NO | R | 04294967 295 |
| 625 | 271 | UO 6 counter timer | Running timer in minutes. Will reset once "counter timer set" reached and start again | NO | R | 014400 |
| 626 | 272 | UO 6 counter timer set | Timer duration configuration in minutes | YES | R/W | 014400 |
| 627 | 273 | UO 6 counter reset | Reset command to all counted values (goes back to "0" automatically) | NO | R/W | 01 |
| 721 | 2D1 | UO 7 counter (totalizer) | 32 bit long, total counter value (totalizer) (pulse input mode) | NO | R/W | 04294967 295 |
| 723 | 2D3 | UO 7 counter (timer) | 32 bit long, counter value for the running timer (pulse input mode) | NO | R | 04294967 295 |
| 725 | 2D5 | UO 7 counter timer | Running timer in minutes. Will reset once "counter timer set" reached and start again | NO | R | 014400 |
| 726 | 2D6 | UO 7 counter timer set | Timer duration configuration in minutes | YES | R/W | 014400 |
| 727 | 2D7 | UO 7 counter reset | Reset command to all counted values (goes back to "0" automatically) | NO | R/W | 01 |
| 821 | 335 | UO 8 counter (totalizer) | 32 bit long, total counter value (totalizer) (pulse input mode) | NO | R/W | 04294967 295 |
| 823 | 337 | UO 8 counter (timer) | 32 bit long, counter value for the running timer (pulse input mode) | NO | R | 04294967 295 |
| 825 | 339 | UO 8 counter timer | Running timer in minutes. Will reset once "counter timer set" reached and start again | NO | R | 014400 |
| 826 | 33A | UO 8 counter timer set | Timer duration configuration in minutes | YES | R/W | 014400 |
| 827 | 33B | UO 8 counter reset | Reset command to all counted values (goes back to "0" automatically) | NO | R/W | 01 |

| Digital Ir | iput Poi | nts | | | | |
|------------|----------|--------------------------|---|--------|------|-----------------|
| Decimal | Hex | Name | Details | Stored | Туре | Range |
| 5001 | 1389 | DI 1 mode | | | | |
| 5002 | 138A | DI 2 mode | | | | |
| 5003 | 138B | DI 3 mode | | | | |
| 5004 | 138C | DI 4 mode | | | | |
| 5005 | 138D | DI 5 mode | | | | |
| 5006 | 138E | DI 6 mode | | | | |
| 5007 | 138F | DI 7 mode | Digital Input mode select: | | | |
| 5008 | 1390 | DI 8 mode | 0 = Digital Input direct 1 = Digital Input reverse | YES | DAV | 0.2 |
| 5009 | 1391 | DI 9 mode | 2 = Pulse input | TES | R/W | 02 |
| 5010 | 1392 | DI 10 mode | | | | |
| 5011 | 1393 | DI 11 mode | | | | |
| 5012 | 1394 | DI 12 mode | | | | |
| 5013 | 1395 | DI 13 mode | | | | |
| 5014 | 1396 | DI 14 mode | | | | |
| 5015 | 1397 | DI 15 mode | | | | |
| 5016 | 1398 | DI 16 mode | | | | |
| 1001 | 3E9 | DI 1 | | | | |
| 1002 | 3EA | DI 2 | | | | |
| 1003 | 3EB | DI 3 | | | | |
| 1004 | 3EC | DI 4 | | | | |
| 1005 | 3ED | DI 5 | | | | |
| 1006 | 3EE | DI 6 | | | | |
| 1007 | 3EF | DI 7 | | | | |
| 1008 | 3F0 | DI 8 | Read Digital Input status (digital input mode): 0 = inactive | NO | R | 01 |
| 1009 | 3F1 | DI 9 | 1 = active | NO | IX. | 01 |
| 1010 | 3F2 | DI 10 | | | | |
| 1011 | 3F3 | DI 11 | | | | |
| 1012 | 3F4 | DI 12 | | | | |
| 1013 | 3F5 | DI 13 | | | | |
| 1014 | 3F6 | DI 14 | | | | |
| 1015 | 3F7 | DI 15 | | | | |
| 1016 | 3F8 | DI 16 | | | | |
| 1111 | 457 | DI 1-16 | Read digital input status by bit (only digital input mode, bit 0 = DI 1) | NO | R | 01 |
| 1121 | 461 | DI 1 counter (totalizer) | 32 bit long, total counter value (totalizer) (pulse input mode) | NO | R/W | 04294967 295 |

| 1123 | 463 | DI 1 counter (timer) | 32 bit long, counter value for the running timer (pulse input mode) | NO | R | 04294967 295 |
|------|-----|--------------------------|--|-----|-----|-----------------|
| 1125 | 465 | DI 1 counter timer | Running timer in minutes. Will reset once "counter timer set" reached and start again | NO | R | 014400 |
| 1126 | 466 | DI 1 counter timer set | Timer duration configuration in minutes | YES | R/W | 014400 |
| 1127 | 467 | DI 1 counter reset | Reset command to all counted values (goes back to "0" automatically) | NO | R/W | 01 |
| 1221 | 4C5 | DI 2 counter (totalizer) | 32 bit long, total counter value (totalizer) (pulse input mode) | NO | R/W | 04294967 295 |
| 1223 | 4C7 | DI 2 counter (timer) | 32 bit long, counter value for the running timer (pulse input mode) | NO | R | 04294967 295 |
| 1225 | 4C9 | DI 2 counter timer | Running timer in minutes. Will reset once "counter timer set" reached and start again | NO | R | 014400 |
| 1226 | 4CA | DI 2 counter timer set | Timer duration configuration in minutes | YES | R/W | 014400 |
| 1227 | 4CB | DI 2 counter reset | Reset command to all counted values (goes back to "0" automatically) | NO | R/W | 01 |
| 1321 | 529 | DI 3 counter (totalizer) | 32 bit long, total counter value (totalizer) (pulse input mode) | NO | R/W | 04294967 295 |
| 1323 | 52B | DI 3 counter (timer) | 32 bit long, counter value for the running timer (pulse input mode) | NO | R | 04294967 295 |
| 1325 | 52D | DI 3 counter timer | Running timer in minutes. Will reset once "counter timer set" reached and start again | NO | R | 014400 |
| 1326 | 52E | DI 3 counter timer set | Timer duration configuration in minutes | YES | R/W | 014400 |
| 1327 | 52F | DI 3 counter reset | Reset command to all counted values (goes back to "0" automatically) | NO | R/W | 01 |
| 1421 | 58D | DI 4 counter (totalizer) | 32 bit long, total counter value (totalizer) (pulse input mode) | NO | R/W | 04294967 295 |
| 1423 | 58F | DI 4 counter (timer) | 32 bit long, counter value for the running timer (pulse input mode) | NO | R | 04294967 295 |
| 1425 | 591 | DI 4 counter timer | Running timer in minutes. Will reset once "counter timer set" reached and start again | NO | R | 014400 |
| 1426 | 592 | DI 4 counter timer set | Timer duration configuration in minutes | YES | R/W | 014400 |
| 1427 | 593 | DI 4 counter reset | Reset command to all counted values (goes back to "0" automatically) | NO | R/W | 01 |
| 1521 | 5F1 | DI 5 counter (totalizer) | 32 bit long, total counter value (totalizer) (pulse input mode) | NO | R/W | 04294967 295 |
| 1523 | 5F3 | DI 5 counter (timer) | 32 bit long, counter value for the running timer (pulse input mode) | NO | R | 04294967 295 |
| 1525 | 5F5 | DI 5 counter timer | Running timer in minutes. Will reset once "counter timer set" reached and start again | NO | R | 014400 |
| 1526 | 5F6 | DI 5 counter timer set | Timer duration configuration in minutes | YES | R/W | 014400 |
| 1527 | 5F7 | DI 5 counter reset | Reset command to all counted values (goes back to "0" automatically) | NO | R/W | 01 |
| 1621 | 655 | DI 6 counter (totalizer) | 32 bit long, total counter value (totalizer) (pulse input mode) | NO | R/W | 04294967 295 |
| 1623 | 657 | DI 6 counter (timer) | 32 bit long, counter value for the running timer (pulse input mode) | NO | R | 04294967 295 |
| 1625 | 659 | DI 6 counter timer | Running timer in minutes. Will reset once "counter timer set" reached and start again | NO | R | 014400 |
| 1626 | 65A | DI 6 counter timer set | Timer duration configuration in minutes | YES | R/W | 014400 |
| 1627 | 65B | DI 6 counter reset | Reset command to all counted values (goes back to "0" automatically) | NO | R/W | 01 |
| 1721 | 6B9 | DI 7 counter (totalizer) | 32 bit long, total counter value (totalizer) (pulse input mode) | NO | R/W | 04294967 295 |

| 1723 | 6BB | DI 7 counter (timer) | 32 bit long, counter value for the running timer (pulse input mode) | NO | R | 04294967 295 |
|------|-----|---------------------------|--|-----|-----|-----------------|
| 1725 | 6BD | DI 7 counter timer | Running timer in minutes. Will reset once "counter timer set" reached and start again | NO | R | 014400 |
| 1726 | 6BE | DI 7 counter timer set | Timer duration configuration in minutes | YES | R/W | 014400 |
| 1727 | 6BF | DI 7 counter reset | Reset command to all counted values (goes back to "0" automatically) | NO | R/W | 01 |
| 1821 | 655 | DI 8 counter (totalizer) | 32 bit long, total counter value (totalizer) (pulse input mode) | NO | R/W | 04294967 295 |
| 1823 | 657 | DI 8 counter (timer) | 32 bit long, counter value for the running timer (pulse input mode) | NO | R | 04294967 295 |
| 1825 | 659 | DI 8 counter timer | Running timer in minutes. Will reset once "counter timer set" reached and start again | NO | R | 014400 |
| 1826 | 65A | DI 8 counter timer set | Timer duration configuration in minutes | YES | R/W | 014400 |
| 1827 | 65B | DI 8 counter reset | Reset command to all counted values (goes back to "0" automatically) | NO | R/W | 01 |
| 1921 | 781 | DI 9 counter (totalizer) | 32 bit long, total counter value (totalizer) (pulse input mode) | NO | R/W | 04294967 295 |
| 1923 | 783 | DI 9 counter (timer) | 32 bit long, counter value for the running timer (pulse input mode) | NO | R | 04294967 295 |
| 1925 | 785 | DI 9 counter timer | Running timer in minutes. Will reset once "counter timer set" reached and start again | NO | R | 014400 |
| 1926 | 786 | DI 9 counter timer set | Timer duration configuration in minutes | YES | R/W | 014400 |
| 1927 | 787 | DI 9 counter reset | Reset command to all counted values (goes back to "0" automatically) | NO | R/W | 01 |
| 2021 | 7E5 | DI 10 counter (totalizer) | 32 bit long, total counter value (totalizer) (pulse input mode) | NO | R/W | 04294967 295 |
| 2023 | 7E7 | DI 10 counter (timer) | 32 bit long, counter value for the running timer (pulse input mode) | NO | R | 04294967 295 |
| 2025 | 7E9 | DI 10 counter timer | Running timer in minutes. Will reset once "counter timer set" reached and start again | NO | R | 014400 |
| 2026 | 7EA | DI 10 counter timer set | Timer duration configuration in minutes | YES | R/W | 014400 |
| 2027 | 7EB | DI 10 counter reset | Reset command to all counted values (goes back to "0" automatically) | NO | R/W | 01 |
| 2121 | 849 | DI 11 counter (totalizer) | 32 bit long, total counter value (totalizer) (pulse input mode) | NO | R/W | 04294967 295 |
| 2123 | 84B | DI 11 counter (timer) | 32 bit long, counter value for the running timer (pulse input mode) | NO | R | 04294967 295 |
| 2125 | 84D | DI 11 counter timer | Running timer in minutes. Will reset once "counter timer set" reached and start again | NO | R | 014400 |
| 2126 | 84E | DI 11 counter timer set | Timer duration configuration in minutes | YES | R/W | 014400 |
| 2127 | 84F | DI 11 counter reset | Reset command to all counted values (goes back to "0" automatically) | NO | R/W | 01 |
| 2221 | 8AD | DI 12 counter (totalizer) | 32 bit long, total counter value (totalizer) (pulse input mode) | NO | R/W | 04294967 295 |
| 2223 | 8AF | DI 12 counter (timer) | 32 bit long, counter value for the running timer (pulse input mode) | NO | R | 04294967 295 |
| 2225 | 8B1 | DI 12 counter timer | Running timer in minutes. Will reset once "counter timer set" reached and start again | NO | R | 014400 |
| 2226 | 8B2 | DI 12 counter timer set | Timer duration configuration in minutes | YES | R/W | 014400 |
| 2227 | 8B3 | DI 12 counter reset | Reset command to all counted values (goes back to "0" automatically) | NO | R/W | 01 |

| 2321 | 911 | DI 13 counter (totalizer) | 32 bit long, total counter value (totalizer) (pulse input mode) | NO | R/W | 04294967 295 |
|------|-----|---------------------------|--|-----|-----|-----------------|
| 2323 | 913 | DI 13 counter (timer) | 32 bit long, counter value for the running timer (pulse input mode) | NO | R | 04294967 295 |
| 2325 | 915 | DI 13 counter timer | Running timer in minutes. Will reset once "counter timer set" reached and start again | NO | R | 014400 |
| 2326 | 916 | DI 13 counter timer set | Timer duration configuration in minutes | YES | R/W | 014400 |
| 2327 | 917 | DI 13 counter reset | Reset command to all counted values (goes back to "0" automatically) | NO | R/W | 01 |
| 2421 | 975 | DI 14 counter (totalizer) | 32 bit long, total counter value (totalizer) (pulse input mode) | NO | R/W | 04294967 295 |
| 2423 | 977 | DI 14 counter (timer) | 32 bit long, counter value for the running timer (pulse input mode) | NO | R | 04294967 295 |
| 2425 | 979 | DI 14 counter timer | Running timer in minutes. Will reset once "counter timer set" reached and start again | NO | R | 014400 |
| 2426 | 97A | DI 14 counter timer set | Timer duration configuration in minutes | YES | R/W | 014400 |
| 2427 | 97B | DI 14 counter reset | Reset command to all counted values (goes back to "0" automatically) | NO | R/W | 01 |
| 2521 | 9D9 | DI 15 counter (totalizer) | 32 bit long, total counter value (totalizer) (pulse input mode) | NO | R/W | 04294967 295 |
| 2523 | 9DB | DI 15 counter (timer) | 32 bit long, counter value for the running timer (pulse input mode) | NO | R | 04294967 295 |
| 2525 | 9DD | DI 15 counter timer | Running timer in minutes. Will reset once "counter timer set" reached and start again | NO | R | 014400 |
| 2526 | 9DE | DI 15 counter timer set | Timer duration configuration in minutes | YES | R/W | 014400 |
| 2527 | 9DF | DI 15 counter reset | Reset command to all counted values (goes back to "0" automatically) | NO | R/W | 01 |
| 2621 | A3D | DI 16 counter (totalizer) | 32 bit long, total counter value (totalizer) (pulse input mode) | NO | R/W | 04294967 295 |
| 2623 | A3F | DI 16 counter (timer) | 32 bit long, counter value for the running timer (pulse input mode) | NO | R | 04294967 295 |
| 2625 | A41 | DI 16 counter timer | Running timer in minutes. Will reset once "counter timer set" reached and start again | NO | R | 014400 |
| 2626 | A42 | DI 16 counter timer set | Timer duration configuration in minutes | YES | R/W | 014400 |
| 2627 | A43 | DI 16 counter reset | Reset command to all counted values (goes back to "0" automatically) | NO | R/W | 01 |

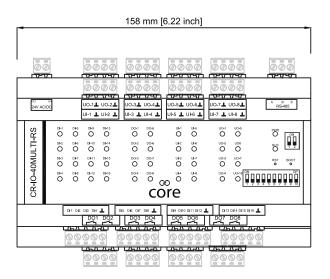
| Universa | Universal Input Points | | | | | | | |
|----------|------------------------|-----------|---|-------|------|---------------------------|--|--------------------------|
| Decimal | Hex | Name | Details | Store | Туре | Range | | |
| 50001 | C351 | UI 1 mode | Universal Input mode select: | | | | | |
| 50002 | C352 | UI 2 mode | 0 = Analog Input 0-10V 1 = Analog Input 2-10V | | | | | |
| 50003 | C353 | UI 3 mode | 2 = Analog Input 0-20 mA 3 = Analog Input 4-20 mA | | | | | |
| 50004 | C354 | UI 4 mode | 4 = PT1000 5 = NI1000 DIN 6 = NI1000 LG | | | | | |
| 50005 | C355 | UI 5 mode | 7 = NTC1K8 8 = NTC2K2 | YES | R/W | 014 | | |
| 50006 | C356 | UI 6 mode | 9 = NTC3K3 10 = NTC10K3A1 11 = NTC10K4A1 | | | | | |
| 50007 | C357 | UI 7 mode | 12 = NTC10KCAREL 13 = NTC20K6A1 14 = Resistor Value | | | | | |
| 50008 | C358 | UI 8 mode | 14 = Resiscor Value | | | | | |
| 10001 | 2711 | UI1 | | | | 0/2-10v and | | |
| 10002 | 2712 | UI2 | | | | 0/4-20mA types -Min | | |
| 10003 | 2713 | UI3 | | | | | | register Max register |
| 10004 | 2714 | UI4 | Read Universal Input value | NO | R | Thermistor | | |
| 10005 | 2715 | UI5 | | | | type – bottom of | | |
| 10006 | 2716 | UI6 | | | | scaling rangetop | | |
| 10007 | 2717 | UI7 | | | | of scaling range (non- | | |
| 10008 | 2718 | UI8 | | | | configurable) | | |
| 20001 | 4E21 | UI 1 min | | | | | | |
| 20002 | 4E22 | UI 2 min | | | | | | |
| 20003 | 4E23 | UI 3 min | | | | | | |
| 20004 | 4E24 | UI 4 min | Minimum value for Universal Inputs | YES | R/W | -10000 | | |
| 20005 | 4E25 | UI 5 min | | | | 10000 | | |
| 20006 | 4E26 | UI 6 min | | | | | | |
| 20007 | 4E27 | UI 7 min | | | | | | |
| 20008 | 4E28 | UI 8 min | | | | | | |

| 30001 | 7531 | UI 1 max | | | | |
|-------|------|-------------|---------------------------------------|-----|-----|--------|
| 30002 | 7532 | UI 2 max | | | | |
| 30003 | 7533 | UI 3 max | | | | |
| 30004 | 7534 | UI 4 max | Maximum value for Universal Inputs YI | YES | R/W | -10000 |
| 30005 | 7535 | UI 5 max | | | | 10000 |
| 30006 | 7536 | UI 6 max | | | | |
| 30007 | 7537 | UI 7 max | | | | |
| 30008 | 7538 | UI 8 max | | | | |
| 40001 | 9C41 | UI 1 offset | | | | |
| 40002 | 9C42 | UI 2 offset | | | | |
| 40003 | 9C43 | UI 3 offset | | | | |
| 40004 | 9C44 | UI 4 offset | Offset value for Universal Inputs | YES | R/W | -10000 |
| 40005 | 9C45 | UI 5 offset | | | | 10000 |
| 40006 | 9C46 | UI 6 offset | | | | |
| 40007 | 9C47 | UI 7 offset | | | | |
| 40008 | 9C48 | UI 8 offset | | | | |



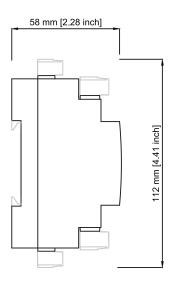
Drawings

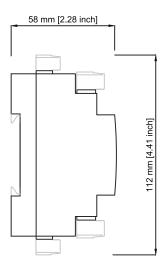
Part number: CR-IO-40MULTI-RS



Part number: CR-IO-40MULTI-IP

| 158 mm [6.22 inch] | | | | | | | | | | | | |
|--------------------|----------------------|-------------|---|---|---------|------|------------------------|---------------|----------|------|--------------|---|
| | | | | | | | | | 000 | 20 | | |
| (*) 24V A | (*) (*) 24V AC/DC | | UO-1 | UO-2 | | UO-4 | UO-5 1 UF5 1 | UO-6 ⊥ | UO-7 📕 U | JO-8 | A B RS-48 | 5 |
| CR-IO-40MULTI-IP | 80 80 80 80 0 8 | BO BO BO BO | 0149 0 01410 0 01411 0 01412 0 | DH 13 OH 14 OH 14 OH 15 OH 16 OH 16 OH 16 | 0 0 0 0 | | o∉ o∉ o∉ o | 05 05 05 05 | 08 08 08 | | RST E | |
| | | | | | | | | | | | & | |
| | | | | | | | | | | | | |





Specifications

| Power supply | 24 Vac +10%/-15% 50 Hz, 24 Vdc +10%/-15% | | | | | |
|------------------------------|---|--|--|--|--|--|
| | Current draw – 80mA min, 200mA max | | | | | |
| | 16 x Digital Inputs (volt free) | | | | | |
| Digital Inputs | DI direct, DI reverse, PULSE (up to 100 Hz, 50% duty cycle, max 50 ohm contact) | | | | | |
| Universal Inputs | 8x selectable inputs Precision reading ±0.5 degrees (PT1000), ±0.1 degrees (NTC), ±0.1 % full scale (active sensor) 21 bits conversion | | | | | |
| oniversut inputs | Passive Inputs: PT1000, NTC10K3A1, NTC10K4A1, NTC1K8, NTC10K CAREL, NTC20K6A1, NTC2.2K, NTC3.3K, NI1000 | | | | | |
| | Active Inputs: 0-10V, 2-10V, 0-20mA, 4-20mA | | | | | |
| | 8 x NO/C relays 230 Vac/30 Vdc, 5 A max, 100.000 cycles | | | | | |
| Digital Outputs | DO direct, DO reverse | | | | | |
| | 8 x universal outputs, precision output ±0.1% of full scale, 12 bits conversion | | | | | |
| Universal Outputs | Analog Outputs: 0-10V, 2-10V, maximum current 20 mA | | | | | |
| | Digital Inputs (volt free): DI direct, DI reverse, PULSE (up to 100 Hz) | | | | | |
| | Digital Outputs (0-10Vdc out, max 20mA): DO direct, DO reverse | | | | | |
| Interface to BEMS | RS485, opto-isolated, max 63 devices supported on the network | | | | | |
| | Ethernet/IP (IP version) | | | | | |
| Protocol to BEMS | Modbus RTU, baud rate 9600 – 230400, 8 bit, no parity, 1 stop bit | | | | | |
| FIULUCULU DEMS | Modbus TCP (IP version) | | | | | |
| Ingress Protection Rating | IP20, EN 61326-1 | | | | | |
| Temperature and | Operating: 0°C to +50°C (32°F to 122°F), max 95% RH (without condensation) | | | | | |
| humidity | Storage: -25°C to +75°C (-13°F to 167°F), max 95% RH (without condensation) | | | | | |
| Connectors | Plug-in Terminals 1 x 2.5 mm2 | | | | | |
| Mounting | Panel mounted (2x on-board sliding screw holders on the back) / DIN rail mounting | | | | | |
| | | | | | | |

Guidelines for Disposal

• The appliance (or the product) must be disposed of separately in accordance with the local waste disposal legislation in force.

• Do not dispose of the product as municipal waste; it must be disposed of through specialist waste disposal centres.

• Improper use or incorrect disposal of the product may negatively affect human health and the environment.

• In the event of illegal electrical and electronic waste disposal, the penalties are specified by local waste disposal legislation.