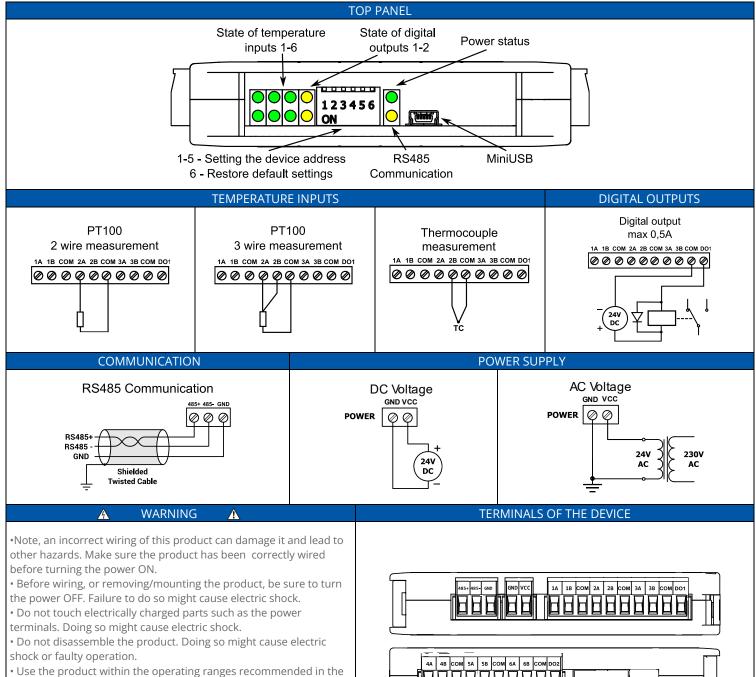
## **SFAR-S-6TI**

## **SPECIFICATION** 10-38 V DC; 10-28 V AC Power supply Power consumption 2,4 W @ 24 V DC 3 V A @ 24 V AC 6x Resistive or thermocouple configurable, resolution 0,1°C 2xTransistor output max 55 V DC, max 500 mA Digital outputs Galvanic isolation Max 1500 Vrms RS485, up to 128 devices on the bus Interface From 2400 to 115200 bps Baudrate IP40 - for indoor installation Ingress protection Temperature Operating -10°C - +50°C; Storage -40°C - +85°C Relative humidity 5 to 95% RH (without condensation) Max 2.5 mm<sup>2</sup> Connectors Dimension 119,1 mm x 101 mm x 22,6 mm DIN rail mounting (DIN EN 50022) Mounting Housing material Plastic, self-extinguishing PC/ABS





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the wires to the terminal might cause fire.

faulty operation.

specification (temperature, humidity, voltage, shock, mounting direction, atmosphere etc.). Failure to do so might cause fire or

· Firmly tighten the wires to the terminal. Insufficient tightening of

## **Registered access**

Modbus	Dec	Hex	Register Name	Access	Description
30001	0	0x00	Version/Type	Read	Version and Type of the device
30002	1	0x01	Switches	Read	Switches state
40003	2	0x02	Baud rate	Read & Write	RS485 baud rate
40004	3	0x03	Stop Bits & Data Bits	Read & Write	No of Stop bits & Data Bits
40005	4	0x04	Parity	Read & Write	Parity bit
40006	5	0x05	Response Delay	Read & Write	Response delay in ms
40007	6	0x06	Modbus Mode	Read & Write	Modbus Mode (ASCII or RTU)
40010	9	0x09	Analog filtering	Read & Write	Configuration analog filtering
40033	32	0x20	Received packets LSR (Least Significant Reg.)	Read & Write	No. of received packets
40034	33	0x21	Received packets MSR (Most Significant Reg.)	Read & Write	
40035	34	0x22	Incorrect packets LSR	Read & Write	
40036	35	0x23	Incorrect packets MSR	Read & Write	No of received packets with error
40037	36	0x24	Sent packets LSR	Read & Write	No of sent packets
40038	37	0x25	Sent packets MSR	Read & Write	
30051	50	0x32	Inputs	Read	Connected sensors Bit in high state → sensor is connected
40052	51	0x33	Outputs	Read & Write	Alarms state bit 6 and 7 alarm outputs
30053	52	0x34	Temperature 1	Read	Temperature or measured
30054	53	0x35	Temperature 2	Read	
30055	54	0x36	Temperature 3	Read	analog
30056	55	0x37	Temperature 4	Read	in mV-10 for voltage to 2048 mV in mV-100 for voltage to 256 mV in °C-10 for temperature in $\Omega$ for resistance
30057	56	0x38	Temperature 5	Read	
30058	57	0x39	Temperature 6	Read	
30059	58	0x3A	Alarm temperature 1	Read	Alarm temperature for alarm output 1
30060	59	0x3B	Alarm temperature 2	Read	Alarm temperature for alarm output 2
30061	60	0x3C	Junction temperature	Read	Module junction temperature
30062	61	0x3D	Measurement current	Read	Measurement current
40063	62	0x3E	MAX alarm level 1	Read & Write	If the temperature exceeds this value the corresponding alarm flag is set
40064	63	0x3F	MAX alarm level 2	Read & Write	
40065	64	0x40	MAX alarm level 3	Read & Write	
40066	65	0x41	MAX alarm level 4	Read & Write	
40067	66	0x42	MAX alarm level 5	Read & Write	

Modbus	Dec	Hex	Register Name	Access	Description
40068	67	0x43	MAX alarm level 6	Read & Write	
40069	68	0x44	MIN alarm level 1	Read & Write	If the temperature is below this value corresponding alarm flag is set
40070	69	0x45	MIN alarm level 2	Read & Write	
40071	70	0x46	MIN alarm level 3	Read & Write	
40072	71	0x47	MIN alarm level 4	Read & Write	
40073	72	0x48	MIN alarm level 5	Read & Write	
40074	73	0x49	MIN alarm level 6	Read & Write	
40075	74	0x4A	Alarm settings 1	Read & Write	
40076	75	0x4B	Alarm settings 2	Read & Write	Alarm settings
40077	76	0x4C	Alarm settings 3	Read & Write	0 – alarm due to the current
40078	77	0x4D	Alarm settings 4	Read & Write	temperature 1 – Remember the value of the
40079	78	0x4E	Alarm settings 5	Read & Write	alarm, until reset by the master via Modbus
40080	79	0x4F	Alarm settings 6	Read & Write	
40081	80	0x50	Constant junction	Read & Write	Value of junction temperature
40082	81	0x51	Junction temperature	Read & Write	Junction temperature offset
40083	82	0x52	Input 1 settings	Read & Write	Analog input mode:
40084	83	0x53	Input 2 settings	Read & Write	0 - input disabled 1 - voltage to 2048 mV 2 - voltage to 256 mV 3 - J thermocouple 4 - K thermocouple 5 - T thermocouple 6 - N thermocouple 7 - S thermocouple
40085	84	0x54	Input 3 settings	Read & Write	
40086	85	0x55	Input 4 settings	Read & Write	
40087	86	0x56	Input 5 settings	Read & Write	
40088	87	0x57	Input 6 settings	Read & Write	
40089	88	0x58	Output 1 settings	Read & Write	Alarm output settings 0 – output is set by PLC +1 – temperature from input 1 +2 – temperature from input 2 +4 – temperature from input 3 +8 – temperature from input 4 +16 – temperature from input 5 +32 – temperature from input 5 +256 – Output is set if value is greater than Alarm Value
40090	89	0x59	Output 2 settings	Read & Write	(register 40091 or 40092) ("cooling") +512 – Output is set if value is less than Alarm Value ( register 40091 or 40092) ("heating") +1024 – The lowest value from selected inputs (if not select either of the two above options than is used average value of selected inputs)

Modbus	Dec	Hex	Register Name	Access	Description
40091	90	0x5A	Alarm Value 1	Read & Write	Alarm value for outputs
40092	91	0x5B	Alarm Value 2	Read & Write	
40093	92	0x5C	Alarm hysteresis 1	Read & Write	The hysteresis value for alarm outputs
40094	93	0x5D	Alarm hysteresis 2	Read & Write	
40095	94	0x5E	Input resistance 1	Read & Write	Lead wire resistance for each input
40096	95	0x5F	Input resistance 2	Read & Write	
40097	96	0x60	Input resistance 3	Read & Write	
40098	97	0x61	Input resistance 4	Read & Write	
40099	98	0x62	Input resistance 5	Read & Write	
40100	99	0x63	Input resistance 6	Read & Write	

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## **INSTALLATION GUIDELINE**





Please read the instruction before use or operating the device. In case of any questions after reading this document, please contact the iSMA CONTROLLI Support Team (support@ismacontrolli.com).





- Before wiring or removing/mounting the product, make sure to turn the power off. Failure to do so might cause an electric shock.
- Improper wiring of the product can damage it and lead to other hazards. Make sure that the product has been correctly wired before turning the power on.
- Do not touch electrically charged parts such as power terminals. Doing so might cause an electric shock.
- Do not disassemble the product. Doing so might cause an electric shock or faulty operation.





- Use the product only within the operating ranges recommended in the specification (temperature, humidity, voltage, shock, mounting direction, atmosphere, etc.). Failure to do so might cause a fire or faulty operation.
- Firmly tighten the wires to the terminal. Failure to do so might cause a fire.
- Avoid installing the product in close proximity to high-power electrical devices and cables, inductive loads, and switching devices. Proximity of such objects may cause an uncontrolled interference, resulting in an instable operation of the product.
- Proper arrangement of the power and signal cabling affects the operation of the entire control system. Avoid laying the power and signal wiring in parallel cable trays. It can cause interferences in monitored and control signals.
- It is recommended to power controllers/modules with AC/DC power suppliers. They provide better and more stable insulation for devices compared to AC/AC transformer systems, which transmit disturbances and transient phenomena like surges and bursts to devices. They also isolate products from inductive phenomena from other transformers and loads.
- Power supply systems for the product should be protected by external devices limiting overvoltage and effects of lightning discharges.
- Avoid powering the product and its controlled/monitored devices, especially high power and inductive loads, from a single power source. Powering devices from a single power source causes a risk of introducing disturbances from the loads to the control devices.
- If an AC/AC transformer is used to supply control devices, it is strongly recommended to use a maximum 100 VA Class 2 transformer to avoid unwanted inductive effects, which are dangerous for devices.
- Long monitoring and control lines may cause loops in connection with the shared power supply, causing disturbances in the operation of devices, including external communication. It is recommended to use galvanic separators.
- To protect signal and communication lines against external electromagnetic interferences, use properly grounded shielded cables and ferrite beads.
- Switching the digital output relays of large (exceeding specification) inductive loads can cause interference pulses to the electronics installed inside the product. Therefore, it is recommended to use external relays/contactors, etc. to switch such loads. The use of controllers with triac outputs also limits similar overvoltage phenomena.
- Many cases of disturbances and overvoltage in control systems are generated by switched, inductive loads supplied by alternating mains voltage (AC 120/230 V). If they do not have appropriate built-in noise reduction circuits, it is recommended to use external circuits such as snubbers, varistors, or protection diodes to limit these effects.



Electrical installation of this product must be done in accordance with national wiring codes and conform to local regulations.

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