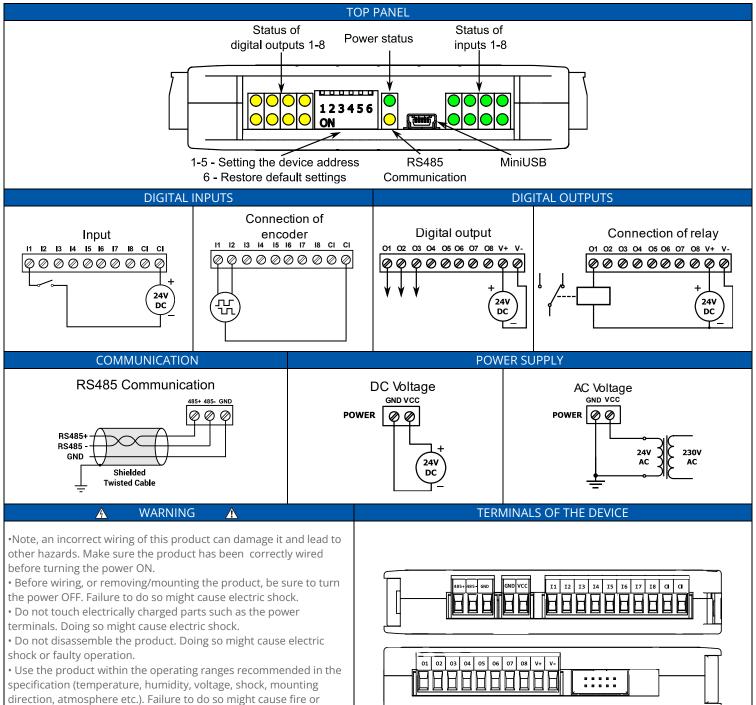
SFAR-S-8DI8DO

SPECIFICATION					
Power supply	Voltage	10-38 V DC; 10-28 V AC			
	Power consumption	2,4 W @ 24 V DC 3 V A @ 24 V AC			
Digital inputs	8xb, logical "0": 0-3 V	8xb, logical "0": 0-3 V, logical "1": 6-36 V			
Digital outputs	8x max 30 V DC, max	8x max 30 V DC, max 500 mA			
Galvanic isolation	Max 1500 Vrms	Max 1500 Vrms			
Interface	RS485, up to 128 dev	RS485, up to 128 devices on the bus			
Baudrate	From 2400 to 115200	From 2400 to 115200 bps			
Ingress protection	IP40 – for indoor inst	IP40 – for indoor installation			
Temperature	Operating -10°C - +50	Operating -10°C - +50°C; Storage -40°C - +85°C			
Relative humidity	5 to 95% RH (without	5 to 95% RH (without condensation)			
Connectors	Max 2.5 mm ²	Max 2.5 mm ²			
Dimension	119,1 mm x 101 mm	119,1 mm x 101 mm x 22,6 mm			
Mounting	DIN rail mounting (DI	DIN rail mounting (DIN EN 50022)			
Housing material	Plastic, self-extinguis	Plastic, self-extinguishing PC/ABS			





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the wires to the terminal might cause fire.

• Firmly tighten the wires to the terminal. Insufficient tightening of

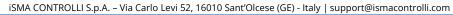
faulty operation.

Registered access

Modbus	Dec	Hex	Register Name	Access	Description	
30001	0	0x00	Version/Type	Read	Version and Type of the	
30002	1	0x01	Switches	Read	Switches state	
40003	2	0x02	Baud rate	Read & write	RS485 baud rate	
40004	3	0x03	Stop Bits & Data Bits	Read & write	No of Stop bits & Data Bits	
40005	4	0x04	Parity	Read & write	Parity bit	
40006	5	0x05	Response Delay	Read & write	Response delay in ms	
40007	6	0x06	Modbus Mode	Read & write	Modbus Mode (ASCII or RTU)	
40009	8	0x08	Watchdog	Read & write	Watchdog	
40013	12	0x0C	Default Output State	Read & write	Default output state (after	
40018	17	0x11	Inputs filter	Read & write	Configuration of the inputs	
40033	32	0x20	Received packets LSR (Least Significant Reg.)	Read & write		
40034	33	0x21	Received packets MSR (Most Significant Reg.)	Read & write	No of received packets	
40035	34	0x22	Incorrect packets LSR	Read & write	No of received packets with	
40036	35	0x23	Incorrect packets MSR	Read & write	error	
40037	36	0x24	Sent packets LSR	Read & write	No of sent packets	
40038	37	0x25	Sent packets MSR	Read & write		
30051	50	0x32	Inputs	Read	Inputs state	
40052	51	0x33	Outputs	Read & write	Output state	
40053	52	0x34	Counter 1 LSR	Read & write	32-bit counter 1	
40054	53	0x35	Counter 1 MSR	Read & write		

Modbus	Dec	Hex	Register Name	Access	Description
40055	54	0x36	Counter 2 LSR	Read & write	0011
40056	55	0x37	Counter 2 MSR	Read & write	32-bit counter 2
40057	56	0x38	Counter 3 LSR	Read & write	
40058	57	0x39	Counter 3 MSR	Read & write	32-bit counter 3
40059	58	0x3A	Counter 4 LSR	Read & write	2011
40060	59	0x3B	Counter 4 MSR	Read & write	32-bit counter 4
40061	60	0x3C	Counter 5 LSR	Read & write	
40062	61	0x3D	Counter 5 MSR	Read & write	32-bit counter 5
40063	62	0x3E	Counter 6 LSR	Read & write	22 h/h
40064	63	0x3F	Counter 6 MSR	Read & write	32-bit counter 6
40065	64	0x40	Counter 7 LSR	Read & write	32-bit counter 7
40066	65	0x41	Counter 7 MSR	Read & write	32-bit counter /
40067	66	0x42	Counter 8 LSR	Read & write	32-bit counter 8
40068	67	0x43	Counter 8 MSR	Read & write	32-bit counter 8
40085	84	0x54	CCounter 1 LSR	Read & write	32-bit value of captured
40086	85	0x55	CCounter 1 MSR	Read & write	counter 1
40087	86	0x56	CCounter 2 LSR	Read & write	32-bit value of captured
40088	87	0x57	CCounter 2 MSR	Read & write	counter 2
40089	88	0x58	CCounter 3 LSR	Read & write	32-bit value of captured
40090	89	0x59	CCounter 3 MSR	Read & write	counter 3
40091	90	0x5A	CCounter 4 LSR	Read & write	32-bit value of captured
40092	91	0x5B	CCounter 4 MSR	Read & write	counter 4

Modbus	Dec	Hex	Register Name	Access	Description
40093	92	0x5C	CCounter 5 LSR	Read & write	32-bit value of captured counter 5
40094	93	0x5D	CCounter 5 MSR	Read & write	
40095	94	0x5E	CCounter 6 LSR	Read & write	32-bit value of captured counter 6
40096	95	0x5F	CCounter 6 MSR	Read & write	
40097	96	0x60	CCounter 7 LSR	Read & write	32-bit value of captured counter 7
40098	97	0x61	CCounter 7 MSR	Read & write	
40099	98	0x62	CCounter 8 LSR	Read & write	32-bit value of captured counter 8
40100	99	0x63	CCounter 8 MSR	Read & write	
40117	116	0x74	Counter Config 1	Read & write	Counter Configuration +1 – time measurement (if 0 counting impulses) +2 – autocatch counter every 1 sec +4 – catch value when input low +8 – reset counter after catch +16 – reset counter if input low +32 – encoder (only for counter 1 and 3)
40118	117	0x75	Counter Config 2	Read & write	
40119	118	0x76	Counter Config 3	Read & write	
40120	119	0x77	Counter Config 4	Read & write	
40121	120	0x78	Counter Config 5	Read & write	
40122	121	0x79	Counter Config 6	Read & write	
40123	122	0x7A	Counter Config 7	Read & write	
40124	123	0x7B	Counter Config 8	Read & write	
40133	132	0x84	Catch	Read & write	Catch counter
40134	133	0x85	Status	Read & write	Captured counter





INSTALLATION GUIDELINE





Please read the instruction before use or operating the device. In case of any questions after reading this document, please contact the iSMA CONTROLLI Support Team (support@ismacontrolli.com).





- Before wiring or removing/mounting the product, make sure to turn the power off. Failure to do so might cause an electric shock.
- Improper wiring of the product can damage it and lead to other hazards. Make sure that the product has been correctly wired before turning the power on.
- Do not touch electrically charged parts such as power terminals. Doing so might cause an electric shock.
- Do not disassemble the product. Doing so might cause an electric shock or faulty operation.





- Use the product only within the operating ranges recommended in the specification (temperature, humidity, voltage, shock, mounting direction, atmosphere, etc.). Failure to do so might cause a fire or faulty operation.
- Firmly tighten the wires to the terminal. Failure to do so might cause a fire.
- Avoid installing the product in close proximity to high-power electrical devices and cables, inductive loads, and switching devices. Proximity of such objects may cause an uncontrolled interference, resulting in an instable operation of the product.
- Proper arrangement of the power and signal cabling affects the operation of the entire control system. Avoid laying the power and signal wiring in parallel cable trays. It can cause interferences in monitored and control signals.
- It is recommended to power controllers/modules with AC/DC power suppliers. They provide better and more stable insulation for devices compared to AC/AC transformer systems, which transmit disturbances and transient phenomena like surges and bursts to devices. They also isolate products from inductive phenomena from other transformers and loads.
- Power supply systems for the product should be protected by external devices limiting overvoltage and effects of lightning discharges.
- Avoid powering the product and its controlled/monitored devices, especially high power and inductive loads, from a single power source. Powering devices from a single power source causes a risk of introducing disturbances from the loads to the control devices.
- If an AC/AC transformer is used to supply control devices, it is strongly recommended to use a maximum 100 VA Class 2 transformer to avoid unwanted inductive effects, which are dangerous for devices.
- Long monitoring and control lines may cause loops in connection with the shared power supply, causing disturbances in the operation of devices, including external communication. It is recommended to use galvanic separators.
- To protect signal and communication lines against external electromagnetic interferences, use properly grounded shielded cables and ferrite beads.
- Switching the digital output relays of large (exceeding specification) inductive loads can cause interference pulses to the electronics installed inside the product. Therefore, it is recommended to use external relays/contactors, etc. to switch such loads. The use of controllers with triac outputs also limits similar overvoltage phenomena.
- Many cases of disturbances and overvoltage in control systems are generated by switched, inductive loads supplied by alternating mains voltage (AC 120/230 V). If they do not have appropriate built-in noise reduction circuits, it is recommended to use external circuits such as snubbers, varistors, or protection diodes to limit these effects.



Electrical installation of this product must be done in accordance with national wiring codes and conform to local regulations.

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